

# **Battle of Postdisaster Response and Restoration**

Diego Paez<sup>1</sup>; Yves Filion, M.ASCE<sup>2</sup>; Mario Castro-Gama<sup>3</sup>; Claudia Quintiliani<sup>4</sup>; Simone Santopietro<sup>5</sup>; Chris Sweetapple<sup>6</sup>; Fanlin Meng<sup>7</sup>; Raziyeh Farmani<sup>8</sup>; Guangtao Fu<sup>9</sup>; David Butler<sup>10</sup>; Qingzhou Zhang<sup>11</sup>; Feifei Zheng<sup>12</sup>; Kegong Diao<sup>13</sup>; Bogumil Ulanicki<sup>14</sup>; Yuan Huang<sup>15</sup>; Jochen Deuerlein<sup>16</sup>; Denis Gilbert<sup>17</sup>; Edo Abraham<sup>18</sup>; Olivier Piller<sup>19</sup>; Alicja Bałut<sup>20</sup>; Rafał Brodziak<sup>21</sup>; Jędrzej Bylka<sup>22</sup>; Przemysław Zakrzewski<sup>23</sup>; Yuanzhe Li<sup>24</sup>; Jinliang Gao<sup>25</sup>; Cai Jian<sup>26</sup>; Chenhao Ou<sup>27</sup>; Shiyuan Hu<sup>28</sup>; Sophocles Sophocleous<sup>29</sup>; Eirini Nikoloudi<sup>30</sup>; Herman Mahmoud<sup>31</sup>; Kevin Woodward<sup>32</sup>; Michele Romano<sup>33</sup>;
Giovanni Francesco Santonastaso<sup>34</sup>; Enrico Creaco<sup>35</sup>; Armando Di Nardo<sup>36</sup>; Michele Di Natale, F.ASCE<sup>37</sup>; Attila Bibok<sup>38</sup>; Camilo Salcedo<sup>39</sup>; Andrés Aguilar<sup>40</sup>; Paula Cuero<sup>41</sup>; Sebastián González<sup>42</sup>; Sergio Muñoz<sup>43</sup>; Jorge Pérez<sup>44</sup>; Alejandra Posada<sup>45</sup>; Juliana Robles<sup>46</sup>; Kevin Vargas<sup>47</sup>; Marco Franchini<sup>48</sup>; Stefano Galelli, M.ASCE<sup>49</sup>; Joong Hoon Kim<sup>50</sup>; Pedro Iglesias-Rey, A.M.ASCE<sup>51</sup>; Zoran Kapelan<sup>52</sup>; Juan Saldarriaga, A.M.ASCE<sup>53</sup>; Dragan Savic, A.M.ASCE<sup>54</sup>; and Thomas Walski, F.ASCE<sup>55</sup>

**Abstract:** The paper presents the results of the Battle of Postdisaster Response and Restoration (BPDRR) presented in a special session at the first International water distribution systems analysis & computing and control in the water industry (WDSA/CCWI) Joint Conference, held in Kingston, Ontario, Canada, in July 2018. The BPDRR problem focused on how to respond and restore water service after the occurrence of five earthquake scenarios that cause structural damage in a water distribution system. Participants were required to propose a prioritization schedule to fix the damages of each scenario while following restrictions on visibility/nonvisibility of damages. Each team/approach was evaluated against six performance criteria: (1) time without supply for hospital/firefighting, (2) rapidity of recovery, (3) resilience loss, (4) average time of no user service, (5) number of users without service for eight consecutive hours, and (6) water loss. Three main types of approaches were identified from the submissions: (1) general-purpose metaheuristic algorithms, (2) greedy algorithms, and (3) ranking-based prioritizations. All three approaches showed potential to solve the challenge efficiently. The results of the participants showed that for this network, the impact of a large-diameter pipe failure on the network is more significant than several smaller pipes failures. The location of isolation valves and the size of hydraulic segments influenced the resilience of the system during emergencies. On average, the interruptions to water supply (hospitals and firefighting) varied considerably among solutions and emergency scenarios, highlighting the importance of private water storage for emergencies. The effects of damages and repair work were more noticeable during the peak demand periods (morning and noontime) than during the low-flow periods; and tank storage helped to preserve functionality of the network in the first few hours after a simulated event. **DOI: 10.1061/(ASCE)WR.1943-5452.0001239.** © *2020 American* 

<sup>1</sup>Former Ph.D. Candidate, Dept. of Civil Engineering, Queen's Univ., 58 University Ave., Kingston, Ontario, Canada K7L 3N9 (corresponding author). ORCID: https://orcid.org/0000-0003-4586-8025. Email: da.paez270@gmail.com

<sup>2</sup>Associate Professor, Dept. of Civil Engineering, Queen's Univ., 58 University Ave., Kingston, Ontario, Canada K7L 3N9.

<sup>3</sup>Researcher, KWR Watercycle Research Institute, Groningenhaven 7, 3433 PE Nieuwegein, Netherlands. ORCID: https://orcid.org/0000-0002 -9081-2672

<sup>4</sup>Researcher, KWR Watercycle Research Institute, Groningenhaven 7, 3433 PE Nieuwegein, Netherlands. ORCID: https://orcid.org/0000-0002 -0841-1360

<sup>5</sup>Ph.D. Candidate, Dipartimento di Ingegneria Civile e Meccanica, Univ. of Cassino and Southern Lazio, Via Gaetano Di Biasio 43, 03043 Cassino, Italy.

<sup>6</sup>Research Fellow, Centre for Water Systems, Univ. of Exeter, North Park Rd., Exeter EX4 4QF, UK.

<sup>7</sup>Associate Research Fellow, Centre for Water Systems, Univ. of Exeter, North Park Rd., Exeter EX4 4QF, UK.

<sup>8</sup>Associate Professor, Centre for Water Systems, Univ. of Exeter, North Park Rd., Exeter EX4 4QF, UK. ORCID: https://orcid.org/0000-0001 -8148-0488

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<sup>9</sup>Senior Lecturer, Centre for Water Systems, Univ. of Exeter, North Park Rd., Exeter EX4 4QF, UK. ORCID: https://orcid.org/0000-0003-1045 -9125

<sup>10</sup>Professor, Centre for Water Systems, Univ. of Exeter, North Park Rd., Exeter EX4 4QF, UK.

<sup>11</sup>Postdoctoral Fellow, College of Civil Engineering and Architecture, Zhejiang Univ., 866 Yuhangtang Rd., Hangzhou 310027, China. ORCID: https://orcid.org/0000-0003-3267-8441

<sup>12</sup>Professor, College of Civil Engineering and Architecture, Zhejiang Univ., 866 Yuhangtang Rd., Hangzhou 310027, China.

<sup>13</sup>Lecturer, School of Engineering and Sustainable Development, De Montfort Univ., Gateway House, Leicester LE1 9BH, UK.

<sup>14</sup>Professor, School of Engineering and Sustainable Development, De Montfort Univ., Gateway House, Leicester LE1 9BH, UK.

<sup>15</sup>Postdoctoral Fellow, College of Civil Engineering and Architecture, Zhejiang Univ., 866 Yuhangtang Rd., Hangzhou 310027, China.

<sup>16</sup>Senior Researcher, 3S Consult GmbH, Albtalstrasse 13, 76137 Karlsruhe, Germany.

<sup>17</sup>Research Engineer, L'unité de recherche Environnement, territoires et infrastructures, Water Dept., Irstea, Bordeaux Regional Centre, Cestas F-33612, France. ORCID: https://orcid.org/0000-0002-3554-1419

<sup>18</sup>Assistant Professor, Faculty of Civil Engineering and Geosciences, Delft Univ. of Technology, Stevinweg 1, 2628 CN, Delft, Netherlands. ORCID: https://orcid.org/0000-0003-0989-5456

<sup>19</sup>Senior Research Scientist, L'unité de recherche Environnement, territoires et infrastructures, Water Dept., Irstea, Bordeaux Regional Centre, Cestas F-33612, France. ORCID: https://orcid.org/0000-0002-3625-7639

# Introduction

A water distribution network (WDN) is one of the critical lifeline systems in a city. Its vulnerability to earthquakes and other natural disasters not only threatens residential, commercial, and industrial activities, but also can affect the capacity to attend to subsequent emergencies. Two of the most analyzed examples in the literature are the January 17, 1994, Northridge earthquake (Los Angeles, California) and the January 17, 1995, Kobe earthquake (Japan). The first case resulted in more than 450,000 people losing water service and at least eight hospitals evacuated due to water and power damages, whereas for the second case, the earthquake affected the supply to more than 1.5 million people and required more than 30 h to extinguish the fires due to water unavailability in many hydrants (PAHO 1998).

Considering the potential vulnerability and key role played by WDN during seismic events, researchers have focused on three main topics: (1) how to assess the reliability of WDNs and other lifelines after extreme seismic events (e.g., Hwang et al. 1998; Wang and O'Rourke 2006; Shi and O'Rourke 2006, Fragiadakis et al. 2013; Liu et al. 2015); (2) how to reinforce the systems to minimize the impact of a given event (e.g., Cimellaro et al. 2015;

<sup>20</sup>Institute of Environmental Engineering, Poznań Univ. of Technology, Berdychowo 4, 60-101 Poznań, Poland. ORCID: https://orcid.org/0000 -0002-2106-1051

<sup>21</sup>Institute of Environmental Engineering, Poznań Univ. of Technology, Berdychowo 4, 60-101 Poznań, Poland. ORCID: https://orcid.org/0000 -0002-7320-355X

<sup>22</sup>Institute of Environmental Engineering, Poznań Univ. of Technology, Berdychowo 4, 60-101 Poznań, Poland. ORCID: https://orcid.org/0000 -0001-8471-4315

- <sup>23</sup>Institute of Computing Science, Poznań Univ. of Technology, Piotrowo 3A, 60-965 Poznań, Poland.
- <sup>24</sup>Dept. of Fluid Control and Automation, Harbin Institute of Technology, Harbin 150090, China.
- <sup>25</sup>School of Municipal and Environmental Engineering, Harbin Institute of Technology, Harbin 150090, China.
- <sup>26</sup>Dipartimento di Ingegneria Civile e Architettura, Harbin Institute of Technology, Harbin 150090, China.

<sup>27</sup>Dipartimento di Ingegneria Civile e Architettura, Harbin Institute of Technology, Harbin 150090, China.

<sup>28</sup>Dipartimento di Ingegneria Civile e Architettura, Harbin Institute of Technology, Harbin 150090, China.

<sup>29</sup>Research Engineer, Centre for Water Systems, Univ. of Exeter, North Park Rd., Exeter EX4 4QF, UK.

<sup>30</sup>Ph.D. Candidate, Centre for Water Systems, Univ. of Exeter, North Park Rd., Exeter EX4 4QF, UK. ORCID: https://orcid.org/0000-0002 -6482-184X

<sup>31</sup>Ph.D. Candidate, College of Engineering, Univ. of Duhok, Zakho St. 38, 1006 AJ Duhok, Kurdistan Region 99454, Iraq.

<sup>32</sup>Strategy Lead, United Utilities Group PLC, Lingley Green Ave., Warrington WA5 3LP, UK.

<sup>33</sup>Senior Engineer, United Utilities Group PLC, Lingley Green Ave., Warrington WA5 3LP, UK.

<sup>34</sup>Ph.D. Candidate, Università della Campania "L. Vanvitelli", Via Roma, 29, 81031 Aversa, Italy.

<sup>35</sup>Associate Professor, Dipartimento di Ingegneria Civile e Architettura, Università di Pavia, Via Ferrata 3, 27100 Pavia, Italy. ORCID: https://orcid .org/0000-0003-4422-2417

<sup>36</sup>Professor, Università della Campania "L. Vanvitelli", Via Roma, 29, 81031 Aversa, Italy.

<sup>37</sup>Professor, Università della Campania "L. Vanvitelli", Via Roma, 29, 81031 Aversa, Italy.

<sup>38</sup>Technical Development Engineer, Budapest Univ. of Technology and Economics, Műegyetem rkp, 3 Budapest, Hungary. ORCID: https:// orcid.org/0000-0003-3992-2881 Yoo et al. 2016); and (3) how to quickly restore the systems to normal/acceptable conditions after the event (e.g., Bonneau and O'Rourke 2009; Wang et al. 2010; Mahmoud et al. 2018). From these, the restoration problem has been the least studied, leaving the prioritization of resources to recover the functionality of the system to the expertise and criteria of utility operators. Considering that lives of people are at stake due to vitality of the supply for firefighting or healthcare purposes, among other considerations, it is imperative to better characterize this problem and evaluate if current knowledge of WDNs can be of use in such circumstances.

The Battle of Postdisaster Response and Restoration (BPDRR) was the eighth call for academic and nonacademic professionals to address a common problem in the water distribution field. Dating back to the first Battle in 1985, this series of competitions have focused on WDNs optimization (1985 and 2012), sensor placement for contaminant intrusion detection in WDNs (2006); WDNs model calibration (2010); leakage assessment in WDNs (2014); district-metered-area sectorization of WDNs (2016); and detection of cyberattacks on WDNs (2017). For this version, the Battle competition focused on the how to respond and restore the service in an existing WDN after the occurrence of five different earthquake scenarios that damaged part of the distribution

<sup>39</sup>Lecturer, Water Distribution and Sewer Systems Research Center (CIACUA), Universidad de los Andes, Bogotá 111711018, Colombia. ORCID: https://orcid.org/0000-0002-0248-7276

<sup>40</sup>Research Engineer, Water Distribution and Sewer Systems Research Center (CIACUA), Universidad de los Andes, Bogotá 111711018, Colombia. ORCID: https://orcid.org/0000-0001-9209-7388

<sup>41</sup>Research Engineer, Water Distribution and Sewer Systems Research Center (CIACUA), Universidad de los Andes, Bogotá 111711018, Colombia.

<sup>42</sup>Research Engineer, Water Distribution and Sewer Systems Research Center (CIACUA), Universidad de los Andes, Bogotá 111711018, Colombia. ORCID: https://orcid.org/0000-0002-3208-9172

<sup>43</sup>Research Engineer, Water Distribution and Sewer Systems Research Center (CIACUA), Universidad de los Andes, Bogotá 111711018, Colombia. ORCID: https://orcid.org/0000-0002-9746-3452

<sup>44</sup>Research Engineer, Water Distribution and Sewer Systems Research Center (CIACUA), Universidad de los Andes, Bogotá 111711018, Colombia.

<sup>45</sup>Research Engineer, Water Distribution and Sewer Systems Research Center (CIACUA), Universidad de los Andes, Bogotá 111711018, Colombia. ORCID: https://orcid.org/0000-0002-7062-1086

<sup>46</sup>Research Engineer, Water Distribution and Sewer Systems Research Center (CIACUA), Universidad de los Andes, Bogotá 111711018, Colombia. ORCID: https://orcid.org/0000-0002-8643-7830

<sup>47</sup>Research Engineer, Water Distribution and Sewer Systems Research Center (CIACUA), Universidad de los Andes, Bogotá 111711018, Colombia.

<sup>48</sup>Professor, Engineering Dept., Università di Ferrara, Via Saragat, 1, 44122 Ferrara, Italy.

<sup>49</sup>Assistant Professor, Pillar of Engineering Systems and Design, Singapore Univ. of Technology and Design, 8 Somapah Rd., Singapore 487372.

<sup>50</sup>Professor, School of Civil, Environmental and Architectural Engineering, Korea Univ., Seoul 02841, South Korea.

<sup>51</sup>Associate Professor, Departamento de Ingeniería Hidráulica y Medio Ambiente, Universidad Politécnica de Valencia, Camino de Vera s/n-46022 (Valencia), Spain. ORCID: https://orcid.org/0000-0001-8300-3255

<sup>52</sup>Professor, Faculty of Civil Engineering and Geosciences, Delft Univ. of Technology, Stevinweg 1, 2628CN Delft, Netherlands.

<sup>53</sup>Professor, Dept. of Civil and Environmental Engineering, Universidad de los Andes, Carrera 1 Este No. 19A-40. Bogotá, Colombia.

<sup>54</sup>Chief Executive Officer, KWR Watercycle Research Institute, Groningenhaven 7, 3433 PE Nieuwegein, Netherlands. ORCID: https:// orcid.org/0000-0001-9567-9041

<sup>55</sup>Bentley Fellow, Bentley Systems, 3 Brians Pl., Nanticoke, PA 18634.

network. The results of the BPDRR were presented in a special session in the first water distribution systems analysis & computing and control in the water industry (WDSA/CCWI) Joint Conference, held in Kingston, Ontario, Canada, in July 2018. This paper summarizes the challenge and results and makes recommendations for future research of the topic.

# **Problem Formulation**

The challenge addressed in the Battle is the one of identifying the best operational response in terms of restoration interventions to return a water distribution network to fully functioning precatastrophic event condition.

After an earthquake, damages to a WDN can degrade the water service in a city. There can be different approaches for prioritization of available resources in order to restore the water service. To evaluate the performance of the different approaches, a set of five postdisaster damage scenarios was generated on a model of the B-City water distribution network, and participants were invited to propose responses and restoration methods to return the system to preearthquake conditions. These damage scenarios, along with a calibrated EPANET model of the network, and a description of the performance criteria, were provided to the participants. The problem description has been given by Paez et al. (2018a).

### **B-City**

B-City is a water distribution network model of a real system in an undisclosed location. The network consists of 4,909 junctions, 6,064 pipes, 1 reservoir, 4 pumps divided between two pump stations, and 5 district metered areas (DMAs), each with one water tank (Fig. 1). A total of 5,963 isolation valves are also distributed along the pipes of the network, delimiting 2,451 segments as defined by Walski (1993). The calibrated model also includes 24-h demand patterns for residential and commercial/industrial consumers. The daily mean consumption on a typical day is 1,023.8 L/s.

For precatastrophic conditions, the minimum pressure during the day among all demand nodes is 24.5 m, which means that the demand is fully supplied (the minimum required pressure is 20.0 m). Additionally, the tanks do not get emptied at any point, and their minimum levels vary from 0.62 to 1.09 m.

## **Damage Scenarios**

One important assumption required to develop the problem was to consider that out of all network elements, only pipes were damaged during the events. In other words, facilities like pump stations, tanks, and the source reservoir were assumed to remain operational at all times. This assumption is consistent with remarks by Tabucchi et al. (2010), and even though PAHO (1998) mentioned examples of tanks and pump stations structurally affected by earth-quakes or disconnected temporally from the electric grid, they are significantly less common than damages in pipelines (Tabucchi et al. 2010).

To stochastically generate pipe damage scenarios, a Poisson process was used (Shi and O'Rourke 2006). Therefore, the probability that a pipe was damaged during the earthquake is given by Eq. (1)

$$P(x_i) = 1 - e^{-\lambda_i L_i} \tag{1}$$

where  $x_i$  = event that pipe *i* is damaged ( $i \in \{1, ..., 6,064\}$ );  $L_i$  = length of the pipe *i* (m); and  $\lambda_i$  = average number of seismic-induced damages per meter for that type of pipe. The values of



**Fig. 1.** B-City water distribution network. Dotted lines delimit DMAs and H represents the hospitals.

 $\lambda_i$  were assumed as 0.0003 damages/m for pipes with diameter under 300 mm and 0.00005 damages/m for larger-diameter pipes, which is a simplification within the ranges presented by the American Lifelines Alliance (2001). This means that the effect of other factors mentioned in the previous studies, like type of soil, pipe material, pipe age, and type of joints, on the probability of damage was assumed homogeneous for all pipes.

According to Ballantyne et al. (1990) and Hwang et al. (1998), the damages in pipes can be classified as leaks, which are minor damages that can be fixed by installing clamps or welding cracks, and breaks, which are more serious damages that require a replacement of entire pipe sections. The conditional probability that a damage was a break was taken as 0.20 for all pipes according to the assumption by Hazards United States (HAZUS) (NIBS 1997) for damages generated by propagation of seismic waves

$$P(y_i|x_i) = 0.20$$
 (2)

where  $y_i$  = event that pipe *i* is broken. It is worth mentioning that according to the HAZUS method, when the damages are caused by a permanent ground displacement, the probability of a break is considerably higher.

After an earthquake disaster, fires are also expected; therefore, firefighting flows must also be supplied. To include them in the model, two nodes per scenario were randomly selected and assigned a fire flow demand of 35 L/s that would only stop until the delivered/supplied water reached 756,000 L (corresponding to a 6 h-duration fire if the flow was fully supplied). The number of fire flow nodes was arbitrarily chosen, and the flow rate was suggested by members of the Committee (Franchini, Galelli,



Using these assumptions, a set of five deterministic postdisaster damage scenarios was generated and provided to the participants, and a likelihood based on the probability of the state of each pipe was assigned to each scenario as a weight for the performance evaluation (computed as the logarithm of the normalized product of individual probabilities for the pipes). Fig. 2 shows one of the five postdisaster damage scenarios as an example.

## **Damages Modeling**

To model the hydraulic effect of damages in the network, an emitter was located at the midpoint of the damaged pipe to simulate its water losses. In order to avoid reverse flows at the emitter (i.e., inflows) caused by negative pressures, a dummy check valve was also included upstream of the emitter. One additional assumption was that breaks in pipes with diameters under 150 mm were assumed to produce a full disconnection between the two ends of the pipe; therefore, the two halves of the pipe were modeled as check valves.

The emitters used to simulate water losses followed Eq. (3), with Eqs. (4) and (5) for the emitter coefficients (Shi and O'Rourke 2006)

$$Q_i(t) = K_i \cdot (h_i(t))^{0.5}$$
(3)

$$K_i = 0.5 \,\mathrm{m} \cdot 0.1^\circ \cdot D_i \cdot \sqrt{2g}$$
 for leaks (4)

$$K_i = \frac{\pi}{2} \cdot 0.5^\circ \cdot D_i^2 \cdot \sqrt{2g} \quad \text{for breaks} \tag{5}$$



where  $Q_i(t)$  = outflow from the emitter *i* at time *t*;  $h_i(t)$  = pressure head at the midpoint of pipe *i* at time *t*;  $D_i$  = diameter of pipe *i*; and  $K_i$  = emitter coefficient that represents a 0.5-m longitudinal crack with an angle of 0.1° for leaks and a 0.5° round crack for breaks (Fig. 3).

To consider that not all damages are immediately detected by the water utilities, some of them were considered nonvisible, meaning that they could not be detected, and therefore fixed, only until some time after the event. Leaks in pipes with a diameter under 300 mm and breaks in pipes with diameter under 150 mm were assumed nonvisible unless they reached an outflow higher than 2.5 L/s (values based on the experience of some members of the Committee). However, 48 h after the event, it was assumed that some pressure tests and inspections would be carried out, making all damages visible after that time. Visibility of damages was important from the network restoration point of view (discussed in the next section).

#### **Response and Network Restoration**

After the occurrence of an earthquake, the water utility would require some reaction time (assumed 30 min here) before the crews can be dispatched to begin the restoration works. There were assumed to be three crews able to work 24 h independently of the turns of each worker, and they could perform four basic tasks: isolate, repair, replace, and reopen.

Both leaking and broken pipes could be isolated by sending a crew to the damage location (even though it is strictly necessary for broken pipes only). It was assumed that the water utility knows the location of all isolation valves in the network, and therefore, isolating a pipe consists of closing all the valves in the hydraulic segment that contains it. Isolation of pipes serves two main purposes: stop water leaking from the network at a certain damage location, and dry the pipes in the segment so they can be replaced if required.

Leaking pipes must be repaired. To repair a leaking pipe, a crew must be sent to the pipe location where they need to locate the leakage, excavate, repair the pipe either with a clamp or by welding, and restore trench conditions. Broken pipes must be replaced. To replace a broken pipe, it must first be isolated, excavated, replaced, and trench conditions must be restored (disinfection and pressure tests are assumed to be omitted in an emergency scenario).

Task	Duration time per pipe
Isolate	15 min/valve
Repair <sup>a</sup>	$0.223 \cdot D_i^{0.577}$
Replace <sup>a</sup>	$0.156 \cdot D_i^{0.719}$

 ${}^{a}D_{i}$  in mm and resulting times in hours (rounded to the lowest hour).

**Table 2.** Example of prioritization schedule

Crew	List of tasks (ordered chronologically)
Crew 01	Isolate P136
	Isolate P283
	Repair P206
	Replace P152
	Repair P242
Crew 02	Isolate P367
	Isolate P152
	Replace P367
	Replace P136
	Repair P154
Crew 03	Isolate P105
	Replace P105
	Repair P254
	Repair P221
	Isolate P133

Finally, an isolation valve could be reopened to restore supply to the affected area, once damages were fixed.

The time each crew was assumed to take to isolate, repair and replace a pipe is given in Table 1, where some simplified relations

$$Q_i(p_i) = \begin{cases} 0 & \text{if } p_i \leq 0\\ \text{QD}_i \left(\frac{p_i}{p_{\text{req}}}\right)^n & 0 < p_i \leq p_{\text{req}}\\ \text{QD}_i & p_i > p_{\text{req}} \end{cases}$$

where  $p_i$  = actual pressure head at node *i*; and  $p_{req}$  = minimum required pressure head to ensure full supply (assumed 20 m here).

The functionality of the system at a certain time t is then defined as the percentage of the total demand that is supplied by the network according to the pressure-driven model [based on the serviceability index discussed by Shi and O'Rourke (2006)]:

Functionality 
$$(t) = 100\% \cdot \sum_{\substack{\text{Demand}\\\text{nodes}}} Q_i(t) / \sum_{\substack{\text{Demand}\\\text{nodes}}} DQ_i(t)$$
 (7)

Fig. 4 shows the expected behavior of the functionality as the network gets gradually fixed. Because the demand varies in time, it is likely that the system can fulfill a higher percentage of the demand during nights, whereas during mornings, when demand



Fig. 4. Time variation of functionality as the system is gradually fixed.

have been adjusted to the data presented by Porter (2016). Transportation times and times for reopening of valves are assumed to be included in the figures and expressions in Table 1.

Participants were required to propose a prioritization schedule for the three crews for each scenario, indicating in which order to isolate, repair or replace damages in the network while following two restrictions: (1) only visible damages could be fixed (details on visible/nonvisible damages have been given in the previous section), and (2) only pipes whose hydraulic segment had been previously isolated could be replaced. Table 2 offers an example of the schedules given by participant teams.

### Performance Criteria

Because the system is working under low-pressure conditions, the pressure-driven method of Paez et al. (2018b) was used to compute nodal supplied flows ( $Q_i$ ) and compare them with demand ( $QD_i$ ) as follows:

 $\rightarrow \text{ enforced by a check valve}$  $\rightarrow \text{ enforced by a throttle control valve}$ (6)  $\rightarrow \text{ enforced by a flow control valve}$ 

increases, the supplied percentage decreases, producing these peaks and troughs in the functionality trend.

For each scenario, the schedules proposed by the participants were evaluated according to six main criteria:

1. Time that the hospitals and the firefighting flows are without supply (Fire & hosp.), calculated as the time step of the simulation times the number of time steps in which the supply/ demand ratio for the hospitals and firefighting flows was less than 0.5

Fire & hosp.

$$= \Delta t \cdot \sum_{\substack{\text{Hospitals and} \\ \text{Firefight nodes}}} \operatorname{count}_{t \in T} \{t | Q_i(t) / DQ_i(t) \le 0.5\} \quad (\min)$$

(8)

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2. Time until the system recovers permanently 95% of its functionality (rapidity of recovery,  $t_{95}$ ), calculated as the last (maximum) time step in which the functionality is lower than 95% (Fig. 4)

$$t_{95} = \max_{t \in T} \{ t | \text{Functionality}(t) \le 95\% \} \quad (\min) \qquad (9)$$

 Accumulated loss of functionality from the occurrence of the disaster until full recovery [Resilience loss (Res. loss)], calculated as the area between the 100% line and the functionality time series (Fig. 4)

Res. loss = 
$$\Delta t \cdot \sum_{t \in T} (100\% - \text{Functionality}(t)) \quad (\% \times \min)$$
(10)

4. Average time across demand nodes, each consumer (network node) is without service (Time no serv.), calculated by multiplying the time step and the number of time steps in which the supply/demand ratio was less than 0.5 for each node, and then dividing by the total number of demand nodes (DN = 4,201):

Time no serv.

$$= \frac{\Delta t}{\mathrm{DN}} \cdot \sum_{\substack{\mathrm{Demand}\\\mathrm{nodes}}} \operatorname{count}_{t \in T} \{ t | Q_i(t) / DQ_i(t) \le 0.5 \} \quad (\min)$$
(11)

5. Number of consumers (network nodes) without service for more than eight consecutive hours (Nodes no serv.), calculated by counting the number of nodes with more than one time step in which the next 8 h had always a supply/demand ratio lower than 0.5

Nodes no serv. = 
$$\operatorname{count}_{\substack{\text{Demand}\\\text{nodes}}} \left\{ i | \operatorname{count}_{t \in T} \left\{ t \left| \frac{Q_i(t - \Delta t)}{DQ_i(t - \Delta t)} \le 0.5 \right. \right. \right. \right\}$$
$$\forall \Delta t \in (0, 8 \text{ h}) \right\} \ge 1 \right\} \quad (\text{nodes})$$
(12)

6. Volume of water lost during the 7 days after the event (Water loss), calculated as the sum of the outflows across all damages in the network times the time step

Water loss = 
$$\Delta t \cdot \sum_{i \in \text{Damages}} \sum_{t \in T} Q_i(t)$$
 (L) (13)

Because there were five scenarios, a total of 30 values had to be reported by each team. To assess an approach, each of the six criteria was averaged among the five scenarios using the likelihoods previously described in the "Damage Scenarios" section as weights, giving as a result one average performance per criteria per team.

For this version of the Battle, it was a deliberate decision not to provide a unified metric to rank the solutions. Instead, it was left to the participants' engineering judgment to prioritize the six criteria as they considered appropriate for the city. This decision was taken by the Committee (Franchini, Galelli, Kim, Iglesias-Rey, Kapelan, Saldarriaga, Savic, and Walski, Battle of the Network Models Committee, unpublished report) as a way to allow different approaches including nonoptimization frameworks in the competition.

#### Postdisaster Response and Restoration Algorithms

Ten teams participated in the BPDRR and submitted their approaches, prioritization schedules, results, and recommendations. This section briefly describes each approach.

Castro-Gama et al. (2018) proposed an implementation based on a preliminary graph theory analysis of the network required to identify neighboring pipes. Second, an  $\varepsilon$ -multiobjective evolutionary ( $\varepsilon$ -MOEA) algorithm (Deb et al. 2005) from an optimization library for Python: Platypus was used to obtain the Pareto front for the six criteria. Decision variables were set as a permutation of the possible interventions. The procedure took into account a constant time of displacement between locations (30 min), which increased the operation time of each crew from the values in Table 1. From the sixdimensional (6D) Pareto front, a single solution per scenario was selected based on a visual analytics approach (Castro-Gama et al. 2017). The  $\varepsilon$ -MOEA solution was also compared with the one obtained using a greedy algorithm. Both methods showed similar outcomes with different prioritization of interventions, although the latter had the advantage of requiring only 30% of the computational time of the former. Finally, four engineering interventions (to increase/decrease the storage capacity or the pump flow) were evaluated for each selected solution and damage scenario.

Sweetapple et al. (2018) developed an approach based upon graph theory and heuristic methodologies. First, graph theory was used to enable identification of hydraulic segments (Meng et al. 2018), and subsequently, the valve operations required to isolate each pipe break. Next, a single performance indicator incorporating all six objectives was developed to enable the problem to be reformulated as a single objective (assuming equal weights). Lastly, actions (i.e., isolations, replacements, and repairs) were allocated to each crew using an adaptation of the nearest neighbor algorithm (Cover and Hart 1967), a greedy optimization heuristic. In this approach, performance was evaluated starting with no actions and adding subsequent actions. Each new action was assigned to the first crew that finished the previously assigned actions. At each stage, the next action selected was the one that provided the greatest performance benefit (represented by the single objective value), given the specified prior actions and not accounting for future actions.

Zhang et al. (2018) proposed a dynamic optimization framework with the objective function consisting of six different metrics summed by introducing weights. To identify an optimal sequencing of recovery actions for each postearthquake scenario, a tailored genetic algorithms-based optimization algorithm was used, where the algorithm operators were modified to identify the optimal sequencing of recovery actions for postdisaster WDNs. The most important feature of the proposed method was that the total number of the decision variables (damaged segments) and the decision variables themselves (e.g., pipes that need to be repaired) could both vary when the hydraulic status of the WDN was updated. That updating process was carried out at the completion of each intervention to the postdisaster WDN, and the final sequencing of recovery actions for each crew was identified. The results provided some insights on how to propose an optimal recovery plan. For instance, certain broken pipes were fixed between particular time stamps to avoid negative effects on the service level at some critical locations.

Deuerlein et al. (2018) proposed greedy heuristics to schedule isolation, repairs, and replacement by minimizing a weighted sum of the objectives. In the disaster response, the trade-off between water loss and the other criteria was explored. The method used graph decomposition techniques to identify the valves that isolated a hydraulic segment for replacement (Deuerlein 2008). The authors also analyzed the network hydraulics and how the depletion of tanks affected service levels. Using these and systematic engineering judgement (Gilbert et al. 2017), recommendations were made for improving the capacity of the system and its absorptive and restorative resilience by design. This included the improvement of pumping stations, installation of control valves, and some pipe reinforcement. The same greedy task-scheduling algorithm was then used under these alternative network improvements to evaluate the improvements with respect to all criteria.

Balut et al. (2018) proposed a ranking-based approach where water network pipes' importance was prioritized and applied in a pipe repair schedule. Several approaches to define the importance and create the rankings were proposed based on hydraulic analyzes (using model under normal operating conditions). Expert knowledge was used, collected via conducted surveys, to define the rankings. Authors surveyed 46 managers, consultants, information technology (IT) specialists, and water distribution modelers from utilities, asking them to list the main criteria that influenced the sequence of repair scheduling, in their opinion. For each disaster scenario, all types of rankings developed (diameter, diameter and distance from the source, diameter and velocity, flow with and without strategic points, and impact of pipes' closure on network's hydraulics) were applied to schedule tasks for all repair teams. Additionally, experts were also asked in the surveys to assign weights to four criteria that addressed the rapidity of recovery, number of nodes without service, and volume of water lost. Results from the rankings were evaluated with use of Visual Promethee, a multicriteria decision aid software, and weights based on the recommendation by the experts. Calculation of hydraulic parameters and evaluation of the final solution based on the six predefined criteria were performed using the EPANET-MATLAB toolkit (Eliades et al. 2016).

Li et al. (2018) proposed a two-stage WDN restoration method based on the EPANET-MATLAB toolkit (Eliades et al. 2016). In the first stage, a shortest-path algorithm and greedy algorithm were used to gain the top priority recovery action for a quick response to the disaster. Firstly, the Dijkstra algorithm was used to calculate the shortest path from water source to hospital and fire point. The flow could be guaranteed to these locations by repairing the damaged point on the path and closing the valves of the damaged pipeline closest to the path. Then the greedy algorithm was used to obtain the restoration order of the remaining pipes. In the second stage, the particle swarm optimization algorithm was used to minimize the total amount of water loss during the restoration process.

Sophocleous et al. (2018) developed a simulation-based response and restoration framework divided into three stages: (1) preprocessing, where the possible interventions for each crew were defined together with the time required to complete each intervention, (2) optimization, where an optimized schedule for fixing each damage was established using the nondominated sorting genetic algorithm II (NSGA-II) and a simplified version of weighting objectives, and (3) restoration planning, where an action plan (i.e., table of interventions ranked by priority) for each crew was identified using the optimum solution from Stage 2. The proposed framework developed a methodology to identify the minimum number of links required to isolate a damaged pipe and enabled simplifying the complexity of the optimization problem by (1) solving two subproblems in sequence (i.e., 2- and 7-day subproblems, based on the visibility of the damages); and (2) allocating to each crew a particular part of the WDN and a specific number of interventions. This was done through the use of a *K*-means clustering–based approach (MacQueen 1967) and engineering judgement (allowing the assumption that in real-life a crew would not be asked to deal with damages spread across the whole network). Simulations were run using the EPANET Programmer's Toolkit linked with the MATLAB optimization tool.

Santonastaso et al. (2018) adopted a strategy to restore the water service after an earthquake following two phases: (1) identification of hydraulic segments, which identified the valves that had to be closed to isolate the pipe that needed to be repaired (Creaco et al. 2010); (2) prioritization of the broken pipes according to a topological metric, based on the idea of primary network (Di Nardo et al. 2017) in order to organize the maintenance interventions after the earthquake. The proposed procedure to rank the pipes to be maintained was stated as follows: (1) compute the betweenness for all pipes in the network; (2) repair or replace leaking or broken pipes with high values of edge betweenness; and (3) repeat Step 2 until no pipes remain to be replaced or repaired.

Bibok (2018) proposed a two-stage approach to the problem. A criticality analysis of network segments was carried out using Bentley System's WaterGEMS. It highlighted critical segments whose size could be reduced by installing additional isolation valves. The visible leaks were determined by an initial hydraulic simulation considering the first 30 min. In the second stage, the optimization problem was reduced to a sorting task, which was carried out by a sorting genetic algorithm. The algorithm's genome was the ordered list of sequentially executed repair events. A swapping operator during mutation was utilized to preserve the consistency of the visible and nonvisible leak lists.

Salcedo et al. (2018) proposed a decision support model based upon a prioritization methodology described as follows. Initially, a diagnosis of the network was done, including the assessment of the impact of each pipe within the network based on its reliability (Luong and Nagarur 2005). Then, a prioritization list was developed considering the weighted sum of seven alternative criteria to assign the maintenance activities to each crew. These alternative criteria included the pressure head at hospitals and fire flow nodes, the functionality of the network after rehabilitating a pipe, water losses, and the time needed to rehabilitate each damaged pipe. The weighted list was evaluated at the end of each time step of the simulation using MATLAB and EPANET Programmer's Toolkit. Finally, the final weights of the decision model were determined using a sensitivity analysis.

# **Results and Discussion**

#### Algorithm Performance

Three main types of approaches can be identified from the submissions. The first type of approach was based on using generalpurpose optimization methods, like MOEA, NSGA-II, and genetic algorithms (Castro-Gama et al. 2018; Zhang et al. 2018; Sophocleous et al. 2018; Bibok 2018). In these approaches, the problem was expressed as an optimal sorting task in which the decision variables were the order in which each damage on the network was fixed. The solution space was all possible permutations of the damages, and the objective functions were either the six criteria from Eqs. (8)–(13), a normalized sum of the six criteria (i.e., a single-objective optimization problem), or a combination of normalization and weighting of the six criteria. The normalization references were the computed range of each criterion (defined by the maximum and minimum values found), or a reference value based on an initial solution. The weights, on the other hand, were

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Table 3. Performance of participant teams in the six defined criteria

						Time	Nodes	
Team	Algorithm	Optimization/ranking criteria	Fire & hosp. (min)	$\substack{t_{95} \\ (\min)}$	Res. loss $(\% \times \min)$	no serv. (min)	no serv. (nodes)	Water los (ML)
Castro-Gama et al. (2018)	Platypus $\varepsilon$ -MOEA	6 (original criteria)	1,411	4.094	13.271	38.8	17.9	67.760
Sweetapple et al. (2018)	Nearest neighbor search	1 (weighted and normalized original criteria)	365	5,154	15,472	49.6	90.06	79,982
Zhang et al. (2018)	Improved genetic algorithm	1 (weighted and normalized original criteria)	147	3,106	10,195	64.1	28.6	60,380
Deuerlein et al. (2018)	Greedy algorithm	1 (weighted relative increase of 5 original criteria)	301	3,918	13,250	54.4	140.3	57,278
Balut et al. (2018)	Pipe/damage rankings $(\times 6)$ + Expert survey	1 (weighted and normalized original criteria)	3,396	5,184	25,988	79.4	212.1	66,580
Li et al. (2018)	Greedy algorithm + PSO	1 (Fire & Hosp. for stage 1 and Res. Loss for stage 2)	1,532	3,902	13,574	364.7	818.0	56,624
Sophocleous et al. (2018)	INSGA-II	1 (normalized original criteria)	2,528	9,510	42,129	86.5	37.6	94,116
Santonastaso et al. (2018)	Pipe/damage ranking (×1)	6 (original criteria)	315	4,845	16,958	50.0	104.9	77,881
Bibok (2018)	Genetic algorithm	1 (normalized original criteria)	234	4,638	15,944	216.6	8.4	73,923
Salcedo et al. (2018)	Pipe/damage rankings ( $\times 5+$ )	1 (weighted and normalized modified criteria)	270	4,471	14,235	46.0	35.6	66,799
Average		•	1,050	4,882	18,102	105.0	149.3	70,132
Note: Top three performance NSGA-II = nonsorted genet	values for each criterion are in bold, with the be ic algorithm.	st performance highlighted with bold italics; MOEA = multi	iobjective evolut	tionary alg	gorithm; PSO	= particle s	warm optir	nization; ar

mostly based on engineering judgment and sense of importance of each criterion after a natural disaster.

The second type of approaches was ranking-based prioritizations, in which different metrics were used to define which pipes should be fixed first according to their importance (Balut et al. 2018; Santonastaso et al. 2018; Salcedo et al. 2018). In these approaches, one or various metrics to measure how important is a pipe with respect to the criteria were proposed and tested (the number of metrics tested is shown in parentheses in the second column of Table 3). The nature of proposed metrics included hydraulic properties of the pipes, hydraulic consequences of individual damages, and graph theory metrics. The objective functions used to evaluate a metric were (1) weighted and normalized sum of the six criteria for Balut et al. (2018); (2) a weighted and normalized sum of scores developed to simplify computation of the six criteria for Salcedo et al. (2018); and (3) the six given criteria for Santonastaso et al. (2018).

Finally, the third type of approaches was based on algorithms that made local optimum choices aiming to find near-optimal solutions (Sweetapple et al. 2018; Deuerlein et al. 2018; Li et al. 2018). In these approaches, which could be viewed as greedy algorithms, an objective function was defined either as a weighted and normalized sum of the six criteria or as one of the six criteria depending on the stage of the optimization. Then, starting at the initial time of the simulation, all possible actions (damage fixing) were evaluated, and the one or ones that produced the highest marginal gain in the objective function were selected to be carried out. That process was repeated every time an action was completed until no more actions remained. Li et al. (2018) used this third type of approach in a first stage of their optimization, followed by an application of a metaheuristic [particle swarm optimization (PSO)].

Table 3 summarizes the reported results for the six criteria, averaged among the five damage scenarios (using the likelihoods as weights), for each team. The top three performance values for each criterion are in bold, with the best performance highlighted with bold italics.

Fig. 5 presents graphically the results of each team in each criterion compared with the average among all teams. Values outside the dotted line (average), outperformed the average of the 10 teams. Three teams (Zhang et al. 2018; Deuerlein et al. 2018; Salcedo et al. 2018), one from each type of approach, had all six criteria outperforming against the average (all their areas are outside the average circle), showing that all three approaches have potential in solving the response and restoration challenge.

# Participants' Remarks

Participants were also encouraged to suggest some mitigation measures that the city could take in order to improve the response and restoration process for other possible scenarios. One factor on which almost all participants seemed to agree was that installing more isolation valves would reduce the size of the hydraulic segments and therefore reduce the impact on the supply of the isolations required to replace a broken pipe.

Castro-Gama et al. (2018) also evaluated the effect of increasing or decreasing the storage and pumping capacity in the network and found that increasing the storage and pumping capacity reduces the initial impact of the event (before the interventions). However, once the fixing schedule is optimized, there is little improvement in the performance criteria. Sweetapple et al. (2018) evaluated the effect of the disconnection of all hydraulic segments in the network and suggested the separation of the most upstream segment to avoid having both Tank T1 and the reservoir isolated simultaneously



**Fig. 5.** Performance comparison of each team with respect to the average (dotted line). Better performance indicated by larger shaded areas: (a) results from Castro-Gama et al. (2018); (b) results from Sweetapple et al. (2018); (c) results from Zhang et al. (2018); (d) results from Deuerlein et al. (2018); (e) results from Balut et al. (2018); (f) results from Li et al. (2018); (g) results from Sophocleous et al. (2018); (h) results from Santonastaso et al. (2018); (i) results from Bibok (2018); and (j) results from Salcedo et al. (2018).

in case pipe damage or a contaminant intrusion occurred in that segment. Li et al. (2018) used pipe damage statistics of the real Wenchuan earthquake in 2008 to suggest pipeline renewals to avoid concrete and gray iron pipes, which seemed to be more vulnerable to this kind of events, while increasing the pipe burial depths to reduce pipe displacement. Finally, Bibok (2018) suggested running in advance combinations of simultaneous hydraulic segments isolation to reduce in advance search space and ease the computation of recommended schedules once the event occurs.

# **General Observations**

After analyzing the results and recommendations of all participants, the main insights are summarized as follows:

All six criteria used to evaluate performance of solutions [Eqs. (8)–(13)] were defined as desirable objectives of a response and restoration method and as metrics that would contribute to better understand the consequences of extreme seismic events. However, the fact that only 1 out of 10 teams used a multiobjective optimization approach using the six criteria would suggest that it is necessary to prioritize some of them, with engineering judgment, according to the perspective and policies of the city in order to make it a mathematically tractable problem that actually provides suitable solutions.

- Different types of approaches presented in this Battle have all potential to find satisfactory solutions to the problem. The use of metaheuristics requires in general more computational effort and, therefore, are useful to develop, in advance, plans to react in the moment a disaster occurs. Greedy algorithms are, in general, fast enough to be run at the moment a disaster occurs, making use of that reaction time mentioned before and adapting to new information on damages easily. Finally, ranking-based approaches are straightforward and quick to use, allowing an almost immediate reaction and an instantaneous reordering when given updated information but, unlike optimization-based approaches, rely on subjective, expert generated list of intervention options to consider.
- The run times for the participants' solutions were not reported because it was not a requirement for the submission (in order to allow the use of any available resource and technique), but the computational requirements of metaheuristic algorithms were mentioned by some participants as a drawback for this type of approach. As explained by Castro-Gama et al. (2018), the use of alternatives like greedy algorithms can reduce the



**Fig. 6.** Average resilience loss versus pipe breaks range per damage scenario.

computational time to 30% of the time required by metaheuristics. However, the potential use of parallelization is expected to make the use of this type of optimization algorithms more suited and faster in future.

- Fig. 6 shows the average Res. loss among all participants versus the range of diameters of broken pipes in each scenario. It also shows how, for this particular network, the WDN gets more affected in its functionality by the size of the largest broken pipe, rather than by the number of breaks in the scenario. For example, Scenario 05 has 10 more pipe breaks than Scenario 03, but because Scenario 03 has a 250-mm pipe broken, it has on average higher resilience loss than Scenario 05, which has all its breaks in pipes with diameters under 200 mm.
- One important factor that drives the resilience of the WDN to these emergency scenarios is the location of isolation valves and the size of hydraulic segments relative to affected areas. All participants agree that having more isolation valves would reduce the impact of repairs and replacement works in the supply.
- On average, the interruptions in the supply to emergencies (hospitals and firefighters) was 17.5 h, although considerable variability was seen among participants and scenarios (in some scenarios, some participants were able to maintain continuous water supply to the emergency nodes, whereas in other cases, the interruption accumulated nearly 72 h). Because most of that demand occurred in hospitals, this suggests the need to install or increase their private storage to autonomously cope with their demand for longer periods of time.
- The functionality time series follows a peaks-and- troughs shape driven by the highs and lows of diurnal water demand in the system. Fig. 7 shows an example of a functionality time series [Scenario 01 by Zhang et al. (2018)] as well as the demand time series. During evenings, the supplied water was more closely matched to the demands, whereas during mornings and noon-time, the effects of the damages and the ongoing repair work were more noticeable. Additionally, water stored in the tanks offered an initial cushion on the functionality, which allowed full supply of the demand during the first few hours after the event.
- Regarding the criteria used to evaluate the performance of each team, a correlation analysis allowed to identify that only the pair  $t_{95}$ -Res. loss has a strong positive correlation (0.92), suggesting that algorithms that minimize one would indirectly minimize the other. This was difficult to know in advance, but it would indicate that in an optimization framework, only five objective functions were necessary to solve the challenge. All other computed correlations were below 0.55, with negative values for the four pairs between Nodes no serv. or Water loss, and  $t_{95}$  or Res. loss.



Fig. 7. Functionality time series for scenario 01 by Zhang et al. (2018).

- A Pareto ranking of the 10 teams showed that six solutions were nondominated (Castro-Gama et al. 2018; Zhang et al. 2018; Deuerlein et al. 2018; Li et al. 2018; Bibok 2018; Salcedo et al. 2018), with Salcedo et al. (2018) dominating three of the four other solutions, followed by Zhang et al. (2018) dominating two, and Deuerlein et al. (2018) and Castro-Gama et al. (2018) dominating one.
- To evaluate the robustness of the approaches, the standard deviation across the five scenarios was computed for each criterion and each team. Fig. 8 compares the standard deviations with the averages (an ideal approach would be closer to the bottom-left corner indicating good average performance and low variability in its results). It can be seen that generally, teams with good performance in a criterion (small average value) also had a small standard deviation in that criterion, indicating that their approaches are also robust (with consistently good results for all five scenarios). Exceptions to this remark are mostly in the Resilience loss criteria, where Teams 1, 6, and 3 (Castro-Gama et al. 2018; Li et al. 2018; Zhang et al. 2018), in that order, had comparatively good average performances, but with high variation between scenarios.
- The coefficients of variation for the six criteria were computed (across the 10 teams). The Nodes no serv., Fire & hosp., and Time no serv. were, in that order, the criteria with highest variability, which would suggest that these might be criteria more difficult to attain.

# Conclusions

The paper summarizes the competition challenge and the results of the BPDRR held in Kingston, Ontario, Canada, in July 2018 as part of the first International WDSA/CCWI Joint Conference. Participants in the BPDRR were tasked with identifying the best strategies to respond and restore water service following five hypothetical earthquake scenarios. A total of 10 teams developed approaches that fell into three broad categories of metaheuristic methods, ranking-based prioritization methods, and near-optimal optimization methods. Six performance criteria were used to evaluate the solutions of the 10 teams: (1) time without supply for



i. Castro-Gama et al. (2018) ii. Sweetapple et al. (2018) iii. Zhang et al. (2018) iv. Deuerlein et al. (2018) v. Balut et al. (2018) vi. Li et al. (2018) vii. Sophocleous et al. (2018) viii. Santonastaso et al. (2018) ix. Bibok (2018) x. Salcedo et al. (2018).

Fig. 8. Average and standard deviation per criteria per team.

hospital/firefighting, (2) rapidity of recovery, (3) resilience loss, (4) average time of no user service, (5) number of users without service for eight consecutive hours, and (6) water loss.

The key findings from the Battle are summarized as follows:

- Even though the six performance measures taken together were used to characterize the appropriateness of the response and restoration solutions, the positive correlation found between some of the criteria suggests that in an optimization framework, it might not be necessary to include all of them.
- All three categories of approaches proved to be appropriate to find satisfactory response and restoration solutions despite important differences in computational requirements among approaches. Metaheuristics, on one hand, seem to be suitable to develop plans beforehand the occurrence of the event because their computational cost limits their application during reaction times. Greedy algorithms, on the other hand, are faster to compute and can also adapt easily to new available information, making them more applicable in the case of an emergency. Finally, rankingbased approaches condense expert knowledge and intuitive criteria to suggest swiftly the recommended interventions to follow.
- The location of isolation valves and the size of hydraulic segments relative to areas affected was found to drive the operational resilience of the system. This highlights the importance of having an adequate location and mapping of isolation valves, as well as a regular maintenance to keep them operational in disaster scenarios.
- The average period of interruption to water supply for hospitals and firefighting flows was 17.5 h and varied considerably across participants and emergency scenarios. This highlights the importance of private water storage for emergency response entities.
- Tank storage helped to preserve functionality in the network but only in the first few hours after an emergency event. This may be specific for the system analyzed, i.e., other WDNs may be able to provide water for longer periods of time.

One important point to mention is that extending the results and conclusions of this Battle to practice requires that the list of assumptions remains valid in the specific systems. This implies that utilities need to have updated models of their networks, with good mapping of their isolation valves, and with trained crews that can perform the required tasks in periods close to the assumed. Moreover, they need to keep sufficient resources and parts to fix the damages and communicate efficiently with their crews. Only then should a risk assessment and evaluation of alternatives based on the methods presented in this competition be performed.

## **Future Research**

Areas for further consideration are identified as follows:

- One aspect that was not explored further was the demand variation that can occur after an earthquake. Depending on the magnitude of the event, commercial and industrial demands can be affected because some businesses would close temporarily while normal conditions are re-established.
- Similarly to the previous point, other important simplification for the problem was not to consider damages to other network elements (e.g., pumps or tanks). Power grids energizing the pumping stations and generators may also be damaged during an earthquake. Communication networks that might be used for monitoring and control operations can also be affected in such scenarios. The effect of this type of damages, as well as their probability of occurrence and the times to fix them, are worth further investigation.
- The relationship between demand and functionality (Fig. 7) suggests that there can be better and worst times to fix damages, especially breaks that require isolation, and therefore might be good to explore idle times for crews where they do not fix anything and wait until a low demand time, as noted by Bibok (2018).

- The impact of catastrophic events such as an earthquake may have a more profound impact on the water quality, which needs to be explored further. If this is the case, then partial water supply during the restoration may be of use for specific water uses only (e.g., toilet flushing), and additional measures may have to be considered (e.g., supply of bottled water).
- Usually, important earthquakes produce collapse of buildings and roads, making some streets unfit due to rubbles. These aspects affect mobility and possibility of working of the crews activated for repairing water pipes. These aspects were not considered in the current Battle but might have a significant impact on actual restoring and repairing actions.
- The simplification of transportation times in Table 1 can not apply in many real cases, especially large cities, because fixing two close damages can be less time consuming than fixing two very separate damages. Future studies could attempt to discard this simplification.
- Other practical assumptions made in the competition included the full availability of spare parts and resources to conduct the interventions to all damages. However, this might not be the case in many cities, and therefore, the impact of limited/unavailable resources on the problem could be explored in future.
- Smart water technologies, such as pressure sensors, hydrophones, and flow meters (Hill et al. 2014), provide a large amount of information on the state of a WDN. Going forward, it would be interesting to understand how these data could aid water utilities in the design of response solutions to earthquakes as well as other catastrophic events.
- Recent Battles have focussed on various events that strongly threaten the performance of a WDN, such as contamination events (Ostfeld et al. 2008), cyber-physical attacks (Taormina et al. 2018), or earthquakes (BPDRR). Although these Battles provide enhanced understanding on the performance of engineering solutions to specific events, there seems to be a lack of knowledge on how these solutions should be merged and implemented into joint contingency plans.
- Due to organizational limitations, this Battle used a disclosed/ open set of five scenarios used by the participant teams to develop, adjust, and evaluate their approaches, instead of a bigger, concealed set of predefined scenarios to be tested after the submission of their methods/algorithms. This implies that some methodologies might not have been oriented to a generic solution of the problem, but to the specific solution of these five scenarios. Future research in the topic could benefit from using training scenarios to feedback and adjust the approaches, and test scenarios to evaluate the approaches' actual performance.

# **Data Availability Statement**

Some or all data, models, or code generated or used during the study, including the EPANET models and the results for each team, are available from the corresponding author by request. Additionally, requests regarding code used by the participants to solve the problem will be directed by the corresponding author to the developers of the code. The supplemental files of this manuscript can be found with the problem description (Paez et al. 2018a) in the website: https://www.queensu.ca/wdsa-ccwi2018/problem -description-and-files.

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